





TOPIC PLAN					
Partn er orga nizati on	UNS				
Торіс	Function of Several Variables				
Less on title	Partial Derivatives				
Lear ning objec tives	 ✓ Students will be able to determine partial derivatives of functions of several variables; ✓ Students will acquire and deal with derivatives of a function; ✓ Students will be able to deal with different problems in everyday life, which require finding partial derivatives of a given function; ✓ Students are encouraged to use technology and different software in their work, while considering problem-based situations. 	Strategies/Acti vities Graphic Organizer Think/Pair/Shar e Modeling			
Aim of the lectu re / Desc riptio n of the pract ical	 The aim of the lecture is to make students able to calculate partial derivatives of a function and apply the derivatives to calculate approximation of functions. The teacher gives the next problem to the students: Find the equation of the tangent plane to z = x² cos(πy) - ⁶/_{xy²} at (2,-1). Find the linear approximation to z = 4x² - ye^{2x+y} at (-2,4). 	Collaborative learning Discussion questions Project based learning Problem based learning			
probl em Previ ous know ledge assu med:	 functions algebraic equations differentiating techniques 	Assessment for learning Observations Conversation s Work sample Conference Check list Diagnostics			











we get $\frac{\partial w}{\partial x} = 2x - y$ To find $\frac{\partial w}{\partial y}$ we regard y as the variable and treat x and z as constants. We get $\frac{\partial w}{\partial y} = -x + 2y + 2z$ To find we regard z as the variable and treat x and y as constants. We get $\frac{\partial w}{\partial z} = 2y + 1$ Students can calculate these derivatives using Mathematica on the following way 🔅 Untitled-1 * - Wolfram Mathematica 10.0 File Edit Insert Format Cell Graphics Evaluation Palettes Window Help $\inf[1] := \mathbf{w} [\mathbf{x}_{,}, \mathbf{y}_{,}, \mathbf{z}_{,}] := \mathbf{x}^{2} - \mathbf{x} \mathbf{y} + \mathbf{y}^{2} + 2 \mathbf{y} \mathbf{z} + \mathbf{z};$ In[3]:= D[w[x, y, z], x] ut[3]= 2 x - y [4] = D[w[x, y, z], y]Out[4] = -x + 2y + 2zIn[5]:= D[w[x, v, z], z] ut[5]= 1 + 2 y plot y derivative y integral zeros more... 🕑 🌞 🖃 0 **(** Quick Check 1 For $u = x^2 y^3 z^4$, find $\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial u}{\partial z}$. We will often make use of a simpler notation: f_x for the partial derivative of f with respect to x and f_y for the partial derivative of f with respect to y. Similarly, if z = f(x, y), then z_x represents the partial derivative of z with respect to x, and z_y represents the partial derivative of z with respect to y.



















b) Marginal productivity of labor is
$$\frac{\partial p}{\partial x} = p_x = 50 \frac{2}{3} x^{-1/3} y^{1/3} = \frac{100 y^{1/3}}{3 x^{1/3}}$$
,

Marginal productivity of capital is

$$\frac{\partial p}{\partial y} = p_y = 50 \frac{1}{3} x^{2/3} y^{-2/3} = \frac{50 x^{2/3}}{3 y^{2/3}}$$

c) For 125 units of labor and 64 units of capital, we have

$$p_x(125,64) = 26\frac{2}{3}$$
 and $p_y(125,64) = 26\frac{1}{24}$

A Cobb–Douglas production function is consistent with the law of diminishing returns. That is, if one input (either labor or capital) is held fixed while the other increases infinitely, then production will eventually increase at a decreasing rate. With such functions, it also turns out that if a certain maximum production is possible, then the expense of more labor, for example, may be required for that maximum output to be attainable.

TANGENT PLANES AND LINEAR APPROXIMATIONS

Earlier we saw how the two partial derivatives f_x and f_y can be thought of as the slopes of traces. We want to extend this idea out a little in this section. The graph of a function z = f(x, y) is a surface in three dimensional space and so we can now start thinking of the plane that is "tangent" to the surface as a point.

Let's start out with a point (x_0, y_0) and let's let C_1 represent the trace to f(x, y) for the plane $y = y_0$ (*i.e.* allowing x to vary with y held fixed) and we'll let C_2 represent the trace to f(x, y) for the plane $x = x_0$ (*i.e.* allowing y to vary with x held fixed). Now, we know that $f_x(x_0, y_0)$ is the slope of the tangent line to the trace C_1 and $f_y(x_0, y_0)$ is the slope of the tangent line to the trace C_2 . So, let L_1 be the tangent line to the trace C_1 and let L_2 be the tangent line to the trace C_2 .

The tangent plane will then be the plane that contains the two lines L_1 and L_2 .

Geometrically this plane will serve the same purpose that a tangent line did in Calculs I. A tangent line to a curve was a line that just touched the curve at that point and was "parallel" to the curve at the point in question. Well tangent planes to a surface are planes that just touch the surface at the point and are "parallel" to the surface at the point. Note that this gives us a point that is on the plane. Since the tangent plane and the surface touch at (x_0, y_0) the following point will be on both the surface and the plane.

$$(x_0, y_0, z_0) = (x_0, y_0, f(x_0, y_0))$$

What we need to do now is determine the equation of the tangent plane.





Now, let's rename the constants to simplify up the notation a little. Let's rename them as follows.

 $A = -\frac{a}{c} \qquad B = -\frac{b}{c}$

With this renaming the equation of the tangent plane becomes,

$$z - z_0 = A(x - x_0) + B(y - y_0)$$

and we need to determine values for A and B.

Let's first think about what happens if we hold y fixed, *i.e.* if we assume that $y = y_0$. In this case the equation of the tangent plane becomes,

$$z - z_0 = A(x - x_0)$$

This is the equation of a line and this line must be tangent to the surface at (x_0, y_0) (since it's part of the tangent plane). In addition, this line assumes







that $y = y_0$ (*i.e.* fixed) and *A* is the slope of this line. But if we think about it this is exactly what the tangent to C_1 is, a line tangent to the surface at (x_0, y_0) assuming that $y = y_0$. In other words,

$$z - z_0 = A(x - x_0)$$

is the equation for L_1 and we know that the slope of L_1 is given by $f_x(x_0, y_0)$. Therefore, we have the following,

$$A = f_x(x_0, y_0)$$

If we hold x fixed at $x = x_0$ the equation of the tangent plane becomes,

$$z - z_0 = B(y - y_0)$$

However, by a similar argument to the one above we can see that this is nothing more than the equation for L_2 and that it's slope is B or $f_y(x_0, y_0)$. So,

$$B = f_y(x_0, y_0)$$

The equation of the tangent plane to the surface given by z = f(x, y) at (x_0, y_0) is then,

$$z - z_0 = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

Also, if we use the fact that $z_0 = f(x_0, y_0)$ we can rewrite the equation of the tangent plane as,

$$z - f(x_0, y_0) = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$
$$z = f(x_0, y_0) + f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

We will see an easier derivation of this formula (actually a more general formula) in the next section so if you didn't quite follow this argument hold off until then to see a better derivation.

EXAMPLE 3 Find the equation of the tangent plane to $z = \ln(2x + y)$ at (-1,3).

Solution There really isn't too much to do here other than taking a couple of derivatives and doing some quick evaluations.

$$f_x(x,y) = \frac{2}{2x+y}$$
 $f_x(-1,3) = 2$

$$f_y(x,y) = \frac{1}{2x+y}$$
 $f_y(-1,3) = 1$

The equation of the plane is then,

z - 0 = 2(x + 1) + 1(y - 3)











Actio n				
Mater ials / equip ment / digita I tools / softw are	<u>The materials for learning</u> are given as a part of references of the of this topic plan; <u>Equipment</u> : classroom, whiteboard, marker in different colours; <u>Digital tools</u> : laptop, projector; <u>Software</u> : Geogebra, Mathematica.	end from		
Cons olidat ion	With the given examples students can consider that the real functions and their derivatives are important for solving real life problems. Students will learn what is a partial derivative of a function and how to calculate it. They can learn how to apply differentiation and derivatives to approximate functions. Students can use technology, different digital tools and software as a help for solving problems, but can also realize that even with technology, solving different everyday problems is difficult without math knowledge.			
Reflections and next steps				
Activiti	es that worked	Parts to be	revisited	
Problem solving, collaboration, using technology Depends of conversati the teached difficulties and then parts.		Depends on the conversation the teacher we difficulties the and then reverse.	he students, in a with students will realize the at students had risit appropriate	
References				
 [1] J. Stewart, Calculus, Thomson Learning, China, 2006. [2] M. L. Bittinger, D. J. Ellenbogen and S.A. Surgent, "Calculus and its applications", Addison-Wesley, 2012. [3] T. Došenović, A. Takači, D. Rakić, Udžbenik iz Matematike II za studente Tehnološkog fakulteta, Univerzitet u Novom Sadu, 2017. 				
[4] https://tutorial.math.lamar.edu/classes/calciii/TangentPlanes.aspx				